Óbuda University Kandó Kálmán Faculty of electrical engineering	Institute of Instrumentation and Autom	ation	
	ufacturing systems II. KMGY2ABN	Е	
Cı	redits: 8		
Specialization: Electrical engineer,			
Subject leader: Dr. Boráros-Bakucz András	Teachers: András Boráros Bakucz P	h.D.	
Prerequisites:			
(codes)	Y 1	1, ,,	
Number of lessons: Lecture: 4 Seminar: Way of marking exam	Laboratory exercise: 3 Cons	sultation:	
(si,e,se):e			
X 1 1 7	ution material		
Students should acquire complex knowledge on autom			
software topic. Other goal is student should be able to	recognize problems and solve them. They s	hould be	as
creative as its is possible. Topics of lessons:			
Topic:		Week	Lessons
Theoretical (T:): industrial robots kinematics and applied	cation.	1.	
T: electrical and mechanical drives of industrial robots.		2.	
T: mechanical parts of industrial robots, grippers and to	ools.	3.	
T: mixed production systems, airplane factory and	l shipyard.	4.	
T: topological planning of production lines.		5.	
T: comparison line- and cell-like production		6.	
- Construction and Construction			
T: intelligent sensors,		7.	
T. Interrigent sensors,		,	
T: visit Continental Automotive Ltd.		8.	
T: visit Visteon Székesfehérvár Ltd.		9.	
T: visit BSCH Electronic Ltd.		10.	
T: discussion of the industrial visits		11.	
T: evaluation of a real production system		12.	
T: evaluation of a real production system		13.	
F. C. W. W. W. C.			
Topic:		Week	
IPC programming with C and C++ programming langu	ages.	1.	
IPC programming, sockets.		2.	
process visualization PERL-TK		3.	
process visualization PERL-TK		4.	
ARM programming.		5.	
ARM programming PWM		6.	
ARM programming CAN and Ethernet		7.	
FPGA basics		8.	
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FPGA soft processors	9.			
FPGA soft processors	10.			
Requirements				
The exam conditions are students have to take a successful test during the semester. This can be a presentation or an				
oral sub exam. The exam is oral one.				
Literature: Sam Cubero:Industrial Robotics: Theory, Modelling and Control ISBN 3-86611-285-8				